

Amendment to the Claims

Please amend the claims as follows:

1. (Currently Amended) A device controller, comprising:

an operation section which can send an operation signal to a device for achieving an original functionality; and

a controlling section for notification ~~notifying~~, at a point in time at which the device becomes able to receive the operation signal from the operation section, that the device has become able to receive the operation signal from the operation section[[,]] by actuating a function that the device has for achieving ~~an~~ the original functionality ~~object~~ to thereby change an operational ~~physical~~ state of the device from a present condition to a condition ~~state~~ that is different from the present condition state of the device,

wherein, immediately after the different condition is achieved, the controlling section completes the notification by changing the operational state of the device from the different condition to the present condition.

2. (Canceled)

3. (Currently Amended) The device controller according to claim 1 [[2]], wherein the device includes;

a driving section for displacing a driven part on the basis of the operation signal from the operation section, and

at the point in time at which the controlling section becomes able to receive the operation signal from the operation section, the controlling section drives the driving section to displace the driven part in a predetermined direction by a predetermined amount, and, immediately after the driven part is displaced in the predetermined amount, drives the driving section to displace the driven part in a direction opposite to the predetermined direction by the predetermined amount.

4. (Currently Amended) The device controller according to claim 7 [[2]], wherein the operation section includes:

an operation section main body that is displaceable within a predetermined range in a vehicle compartment, and
detecting sections, with each detecting section being connected to the controlling section and detecting the operation section main body at different positions within the predetermined range,

the device is mounted in the vehicle, and

the operation section can send the operation signal to the device when the operation section main body is in a position corresponding to the device within the predetermined range.

5. (Currently Amended) The device controller according to claim 3, wherein the operation section includes:

an operation section main body that is displaceable within a predetermined range in a vehicle compartment, and
detecting sections, with each detecting section being connected to the controlling section and detecting the operation section main body at different positions within the predetermined range,

the device is mounted in the vehicle, and

the operation section can send the operation signal to the device when the operation section main body is in a position corresponding to the device within the predetermined range.

6. (Currently Amended) The device controller according to claim 2, wherein the operation section includes:

an operation section main body that is displaceable within a

predetermined range in a vehicle compartment, and
detecting sections, with each detecting section being connected to the
controlling section and detecting the operation section main body at
different positions thereof within the predetermined range,

the device is mounted in the vehicle, and

when one detecting section detects the operation section main body, the
operation section can send the operation signal to the device that corresponds to the
detecting section, and

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a direction indicated by the operation section main body substantially
corresponds to a position of the device corresponding to the detecting section.

7. (New) A device controller, comprising:

an operation section which can send an operation signal to a device, for
achieving an original functionality, disposed at a position spaced apart from the
operation section; and

a controlling section which, at a point in time at which the controlling section
becomes able to receive the operation signal from the operation section,

changes an operational state of the device from a current condition to a
condition that is different from the current condition of the device by actuating a
function that the device has for achieving the original functionality, and

immediately returns the device, after achieving the different condition, to
the current condition by again actuating the function of the device for achieving the
original functionality.
